



The NPOI: Description and Design Considerations

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Purpose of Talk

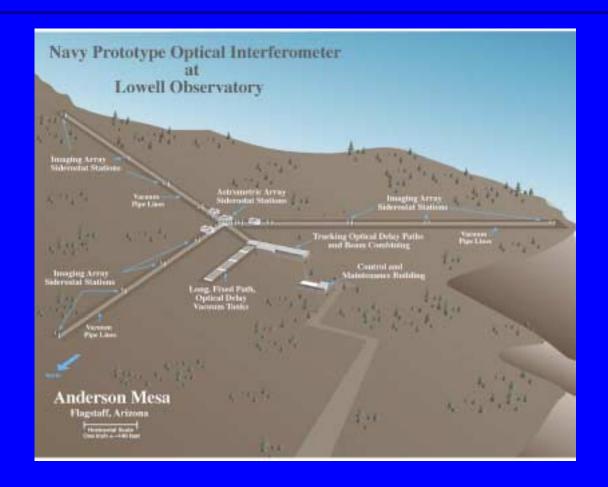


- Provide a Description of the NPOI
- Show how the general ideas presented earlier this week influence the design of an actual instrument.
- Give an Introduction to data reduction procedures which will be needed later today.



NPOI Site







NPOI







NPOI view







Components of an Interferometer



- 1. Array Stations Aperture, Geometry
- 2. Angle Tracking FSM, Sensors
- 3. Beam Transport Vacuum, Geometry Dispersion, Polarization and Beam Rotation
- 4. Delay Compensation Course and Fine
- 5. Beam Combination
- 6. Fringe Detection



I. Array Elements



- NPOI uses Siderostats (Flat Primary)
- Great for Astrometry
 - Mark III Heritage
 - Metrology System
- Reasonable for Small Apertures
 - Feed Direction Elevated 20 Degrees to give better Sky Coverage.



Telescope







Array Geometry



- 6 Elements in a Partially Redundant Y
 - 3 Elements on Each of Three Arms
 - Two arms at a time.
 - Reconfigures with Multiplier of 1.7
 - 10 Stations per Arm.
- Longest Baseline 435 meters
 - Resolution ~ 1 nanoRadian = 0.2 mas



II. Angle Tracking



- The NPOI Includes no Pupil Management
 - On Axis Design → No Problem
- Angle Tracking Errors Translate into Beam Shear
- Fast Steering Mirror Located at Telescope
 - Shear θ L = 3.5 mm
 - One Arc Second
 - 700 Meters
- Angle Sensing at Back end (discussed later)



Angle Tracker







Array Station

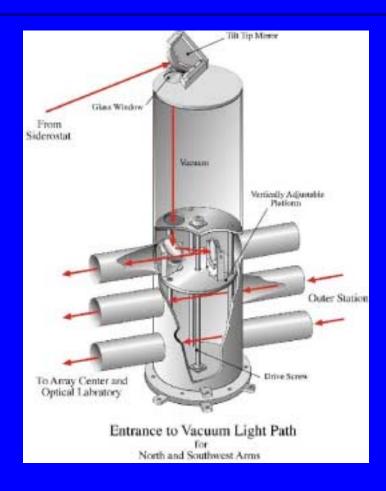






North Arm







III – Beam Transport



- Even though the Feed System Looks Easy, there are a Number of Design Considerations.
 - Differential Refraction
 - Diffraction
 - Set Beam Diameter through Feed System
 - Dispersion
 - Beam Rotation
 - Polarization Effects



Dispersion



- Through most media, the optical path length depends on wavelength
- If the arms of the interferometer are not matched, different wavelengths will interfere at different delays and the visibility of a broadband channel will be reduced.



Group Delay



• If we replace some of the optical path with a dispersive material,

$$\varphi = \frac{2\pi[d_V + (n-1)d_A]}{\lambda} = \frac{2\pi[d_V + (n_0 + n_1\lambda + f_\lambda)d_A]}{\lambda}$$

$$= \frac{2\pi[d_V + n_0d_A]}{\lambda} + n_1d_A + f_\lambda d_A / \lambda$$

• The constant and linear portions of the index of refraction shift the fringe and fringe packet but do not impact the observed visibility amplitudes.



Dispersion Compensation



 Adding Glass to the Optical Path can Compensate Reasonably well for the Air Mismatch Between Arms

• We Chose to Keep the Entire Optical Path in Vacuum.



Internal Seeing



- Even if you (mistakenly?) think you can handle the dispersion, the Feed system should be in vacuum to prevent seeing problems with long near ground optical paths. Especially Important for
 - Long Path lengths
 - Large beam diameters



NPOI Vacuum Seals





- Very low cost
- Maintenance is an issue, but not severe
- Mechanical design is MUCH more subtle than it appears



Feed System Pipes







West Arm







Beam Rotation and Retardation

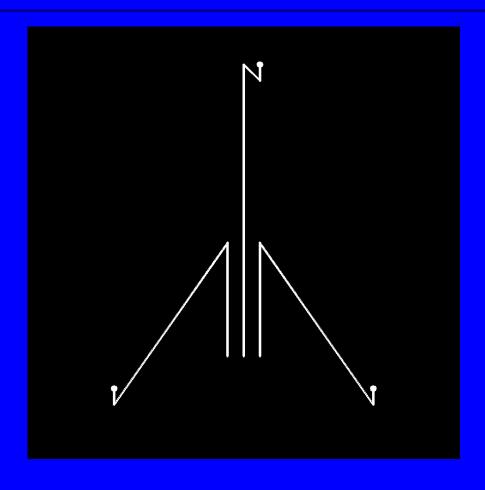


- Visibility Loss can occur from Field Rotation and polarization mismatch between the arms of the interferometer
- Easiest Solution
 - Make all arms identical
 - And in plane rotations commute



Optical Layout







Array Center

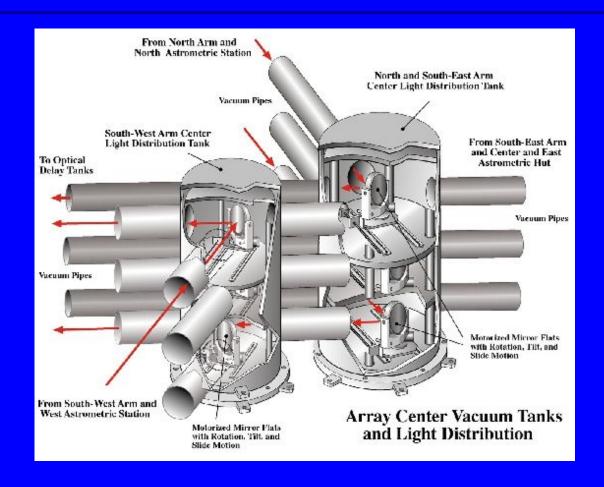






Array Center Details

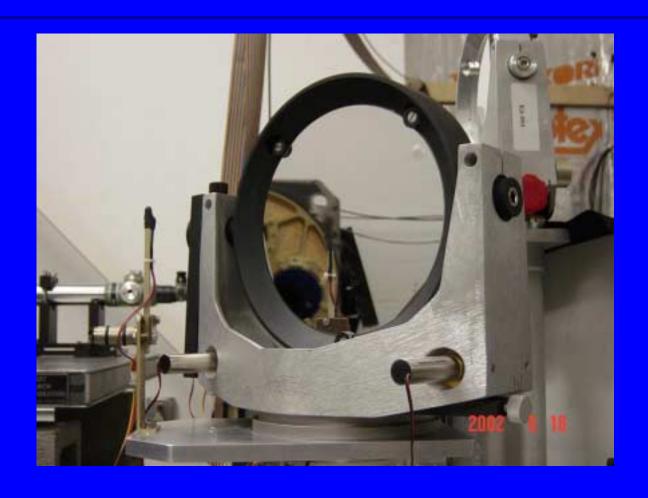






All Mirror Mounts Are Automated







IV – Delay Compensation

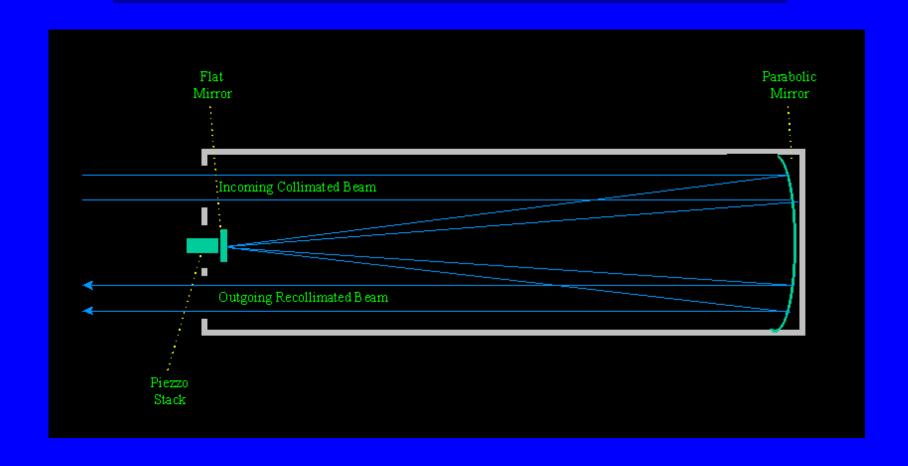


- Divided into two parts
 - FDL Fast delay lines Fringe tracking
 - Retroreflector design for Continuous motion
 - Maximum Delay 35 meters
 - 30 minutes fringe tracking on 500 m baseline
 - 2 cm/sec with 10 nm rms
 - LDL Long delay lines
 - Flat Mirrors Delay added in 30 meter segments
 - Maximum Delay 480 meters



FDL cart







Optics Carts







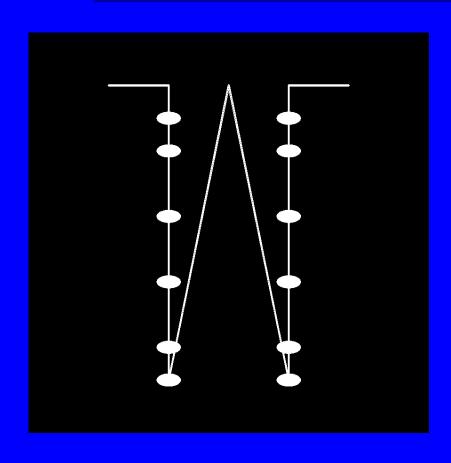
FDL Assembly







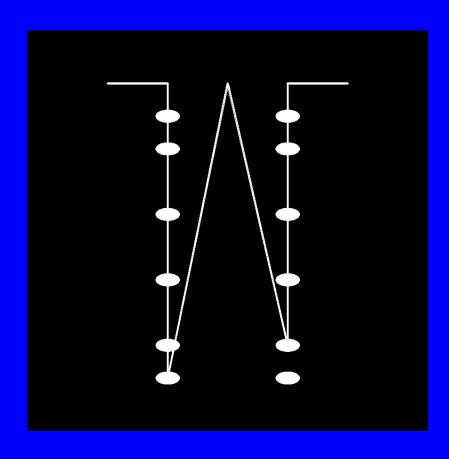




Stn	Dist.	Meters	
1	0	0	
2	1	30	
3	3	90	
4	5	150	
5	7	210	
6	8	240	
Stn $6+6 = 480$ meters			



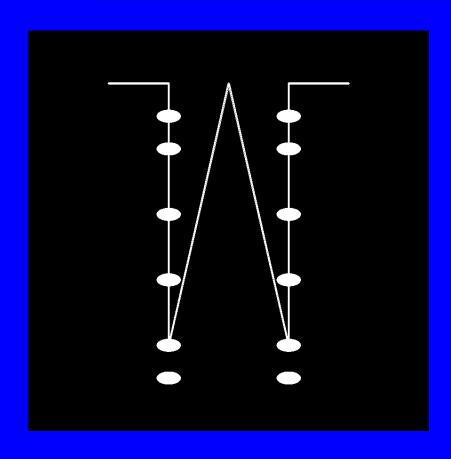




Stn	Dist.	Meters	
1	0	0	
2	1	30	
3	3	90	
4	5	150	
5	7	210	
6	8	240	
8 tn 6 + 5 = 450 meters			



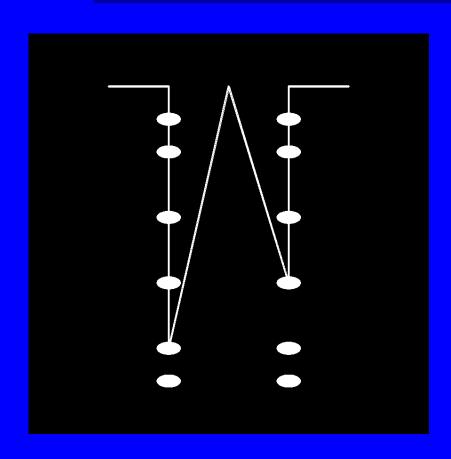




Stn	Dist.	Meters		
1	0	0		
2	1	30		
3	3	90		
4	5	150		
5	7	210		
6	8	240		
Stn 5 + 5 = 420 meters				



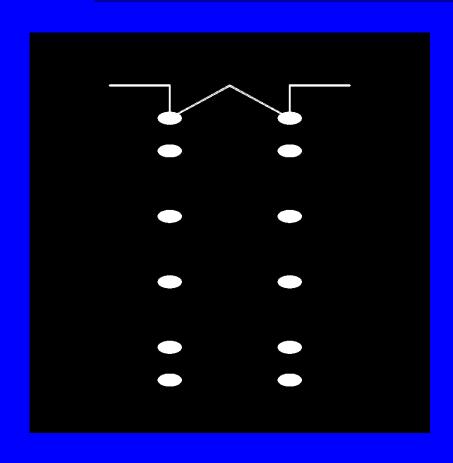




Stn	Dist.	Meters	
1	0	0	
2	1	30	
3	3	90	
4	5	150	
5	7	210	
6	8	240	
Stn $5+4 = 360$ meters			







Stn	Dist.	Meters
1	0	0
2	1	30
3	3	90
4	5	150
5	7	210
6	8	240
Stn $0+0=0$ meters		



LDL Starlight view







LDL Station Details







LDL







LDL Pipes







Bridge







NPOI Long Delay Lines



- The NPOI LDLs violate the symmetry rule.
 - The middle mirror is above the plane of the other mirrors
 - Worst case beam rotation 0.5 degrees
 - − Visibility loss < 0.1%



V – Beam Combination

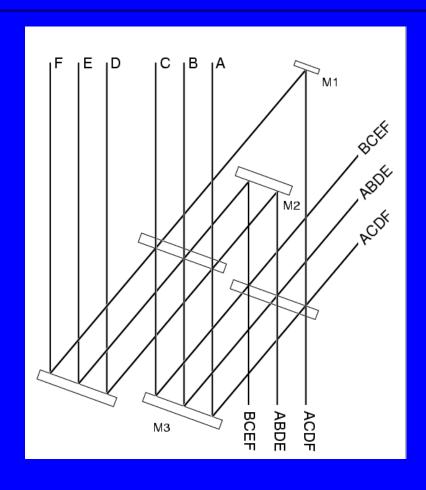


- 3, 4-on-one Combiners run in Parallel
- Unpleasant Trade Between
 - Too long a Modulation
 - Too many Detectors



Beam Combiner Schematic







Beam Combiner Implementation







Fringe Analysis



- Wide Bandpass is needed
 - Sensitivity
- Narrow Bandpass is needed
 - Long Coherence time
 - Science
- Solution Spectrograph in combined beam
- Detectors Photon counting array of APDs
 - Built with lenslet array and single detectors



Fringe Analysis Spectrograph

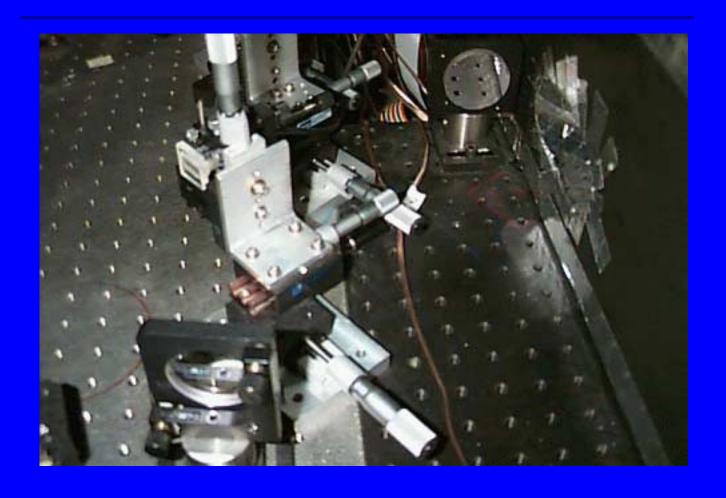






Lenslet Array







APD Array







Angle Sensing



- Located in Beam Combiner with actuator at Telescope
- Implementation
 - Photon Counting Quad Cell
 - 2x2 Lenslet array feeds fibers feeds APDs
 - Central hole in Quad improves sensitivity
 - Error signal is in units of image diameter



Angle Tracker







Fringe Detection

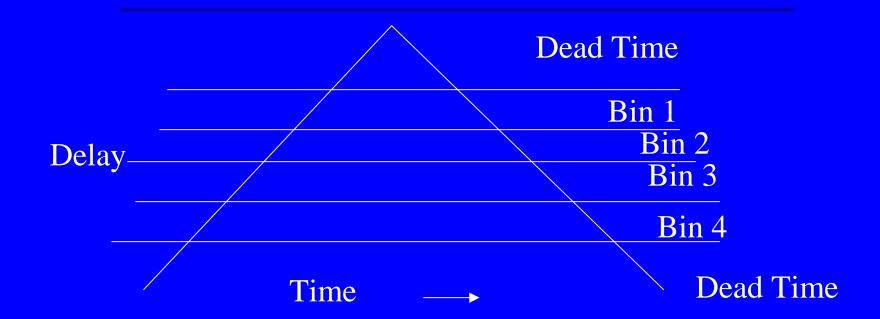


- We use a temporal fringe modulation
 - Modulation occurs in FDL
- Delay Varies with time
- Photons are detected synchronously with modulation
- Data is binned into increments of similar delay called Bins



Fringe Modulation Details





The modulation is a even number of wavelengths at all wavelengths. Dead Time varies with Wavelength



Multiple Baseline Demodulation

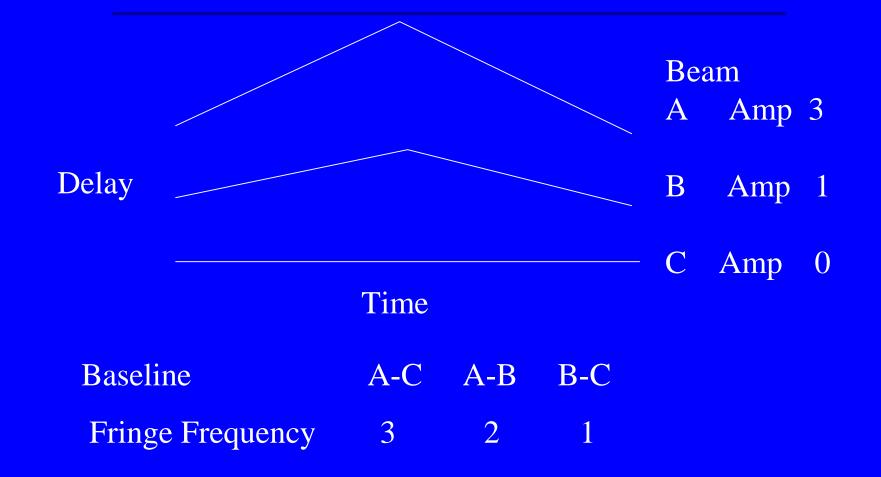


- Each Telescope has a different Modulation Amplitude
- The Difference in Modulation Amplitude between two Beams gives the fringe frequency on that baseline
- No two Baselines on the same Detector have the same Fringe Frequency.



Fringe Detection

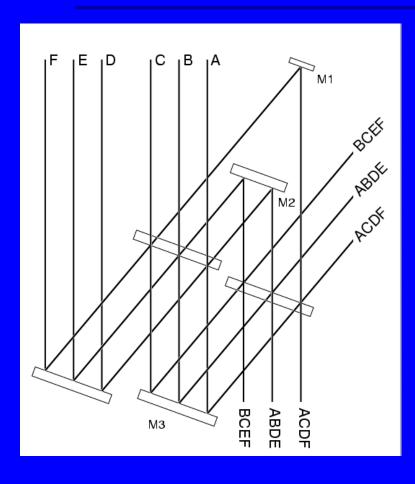






Modulation Scheme





- Modulation
 - ABCDEF
 - -021568
- A-C-D-F
 - -1, 5, 8, 4, 7, 3
- A-B-D-E
 - -2, 5, 6, 3, 4, 1
- B-C-E-F
 - -1, 4, 6, 5, 7, 2



VI – Fringe Analysis



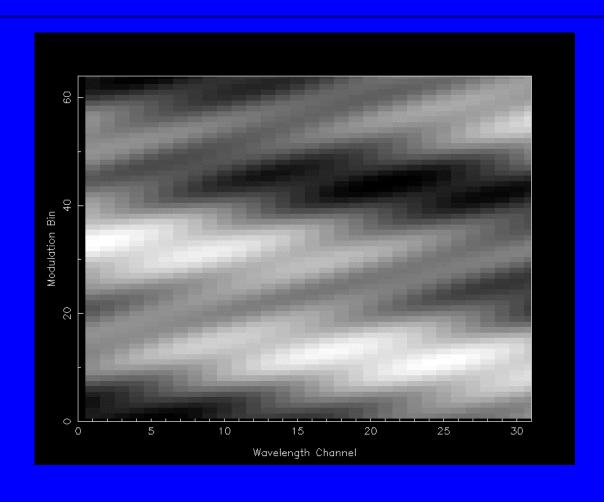
- Data are a Data Cube:
 - Intensity versus Wavelength and bin
 - 64 Bins evenly Sample k Wavelengths
- The Signals Sine Waves buried in Noise

• The Goal is Simple, Unbiased estimate of the Amplitude and Phase of Each Signal.



Data frame

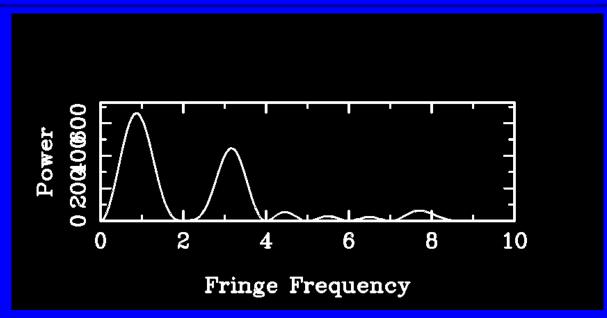






Fringe Spectra





- Fourier Transform of Bin Counts
- Amplitude and Phase at a Frequency Corresponding to the Fringe Frequency of a Baseline is the Complex Visibility for that baseline



Calibration, Bias and Crosstalk



Definitions

- Calibration. A Multiplicative Factor Affecting the Visibility Amplitude $V^2 = \eta \gamma^2$
- Bias. And Additive factor affecting the Visibility Amplitude $V^2 = \gamma^2 + \beta$
- Crosstalk. The Visibility Amplitude for one Baseline Depends on the Measured Amplitudes for the other Baselines. $V_k^2 = \gamma_k^2 + \sum_{j \neq k} \kappa V_j^2$



Calibration



 Calibration Should be Performed Separately for Each affect that Reduces the Fringe Contrast.



Calibration



- Calibration Should be Performed Separately for Each affect that Reduces the Fringe Contrast.
- This is not Done.
- Because Calibrations are Multiplicative, it is possible to lump them together and do a Single Calibration off a Nearby Star.



Example: Photometric Calibration



$$I = \sum_{i} I_{i} \left(1 + 2 \sum_{k,l} \frac{\sqrt{I_{k}I_{l}}}{\sum_{i} I_{i}} \gamma_{k,l} COS(\frac{2\pi d}{\lambda} + \phi_{k,l}) \right)$$

- Relative Brightness of Stars Enters Linearly when more than two Beams are present
 - Quadratic for Pair-wise



Bias



• The Only Bias Term in Optical Interferometry is due to detector Statistics



Fringe Detector Statistics: Bias



- Squared Visibility is the value of the Fringe Power Spectrum at the Fringe Frequency
 - Value always > 0
 - V² biased by the Detector Statistics

$$V^{2} = 4 \frac{\left\langle X^{2} + Y^{2} \right\rangle - \left\langle \sigma^{2}(I) \right\rangle}{\left\langle I \right\rangle^{2}}$$

- intrinsically a correlation measurement
 - Depends on the Second Moment of Detector Statistics



Fringe Detector Statistics: Crosstalk



- For Photon noise Bias correction is Easy.
- Non-Photon noise is a problem
 - Needs Lots of Data to Characterize
- Dead time like corrections
 - Variance is quadratic in count rate
 - Causes Cross-talk



Crosstalk from Detector Statistics



• When More than One Baseline is on the Same Detector and the Detector Statistics are non-Linear, there is inherent Cross talk between the Baselines

$$V_{j}^{2} = 4 \frac{\langle X^{2} + Y^{2} \rangle - \sigma^{2}(\langle I \rangle)}{\langle I \rangle^{2}} - \mu \sum_{i} V_{i}^{j}$$

$$\sigma^2(I) = \alpha + \beta I + \mu \sigma^2$$



Crosstalk



- Everything causes crosstalk
 - Detector Statistics
 - Atmospheric Fringe Motion
 - Non-linear detectors



The Control Room







Atmospheric Fringe Motion



- Atmospheric Turbulence Causes an Error in Fringe Frequency
 - t0 is the time it takes a fringe to move 1 radian

$$\Delta V = V_{atm} = \lambda / 2\pi t_0$$

$$V_{mod} = k\lambda / t_{mod}$$

$$\frac{\Delta f}{f} = \frac{\Delta V}{V} = \frac{t_{mod}}{2\pi t_0 k}$$